



Blind Spot Safety with Thermal Image Processing for Heavy Vehicles

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Abstract: Growing safety concerns for heavy vehicles have prompted significant advancements in blind spot detection systems. Blind spots in heavy vehicles pose risks of accidents, especially under poor visibility conditions. This paper proposes a thermal image processing-based system to enhance blind spot safety. The system uses thermal cameras to detect heat signatures, identifying pedestrians, cyclists, and other vehicles in blind spots, even in low light or adverse weather. Advanced image processing algorithms and machine learning techniques are employed to classify detected objects and trigger real-time alerts for drivers. A prototype was tested under various environmental conditions, demonstrating improved detection accuracy and reduced response time. The findings suggest that integrating thermal imaging with existing driver-assistance technologies can significantly enhance situational awareness, mitigate accidents, and improve road safety for heavy vehicle operations. Potential applications extend to fleet management and automation in transportation..

Keywords – Blind Spot Safety, Heavy Vehicles, Machine Learning, Object Detection, Thermal Imaging.

I. INTRODUCTION

Blind spots in heavy vehicles present significant challenges for road safety. These areas, not visible to drivers through mirrors or cameras, account for numerous accidents involving pedestrians, cyclists, and smaller vehicles. Adverse weather conditions further exacerbate the problem, making it critical to address these visibility gaps effectively.

Traditional methods such as mirrors and cameras, while helpful, often fail under low-light or poor weather conditions, where visibility is already compromised. In such scenarios, drivers are at a heightened risk of missing nearby obstacles, which could lead to catastrophic accidents. Moreover, heavy vehicles, due to their larger size and complex structure, inherently possess more extensive blind spots compared to smaller vehicles, necessitating advanced solutions.

Thermal image processing offers a groundbreaking approach to addressing this issue by leveraging infrared technology to detect heat signatures. Unlike traditional optical methods, thermal imaging is unaffected by lighting conditions, making it highly effective even in complete darkness or foggy environments. By capturing and analyzing heat data, it becomes possible to identify pedestrians, animals, and other vehicles that might otherwise go unnoticed.

This paper explores the integration of thermal imaging technology with machine learning algorithms to enhance blind spot safety. The proposed system not only detects objects but also classifies them, providing real-time alerts to drivers. Such advancements can significantly reduce accident rates, enhance operational safety, and set a new standard for heavy vehicle safety systems.

II. METHODOLOGY

The proposed system involves:

2.1 Hardware Components

- Thermal Camera: Captures infrared images of the surroundings.
- Processing Unit: Converts thermal data into actionable information using advanced algorithms.
- Power Supply: Provides consistent energy for system operation.
- Alert System: Audio and visual alerts for detected hazards.

2.2 Software Implementation

- Image acquisition and preprocessing to enhance thermal images.
- Object detection using edge detection and contour mapping.
- Classification using machine learning algorithms, distinguishing humans from other objects.
- Real-time decision-making and alerts based on object type and proximity.

The system architecture combines thermal imaging with existing Advanced Driver Assistance Systems (ADAS) for comprehensive safety coverage.

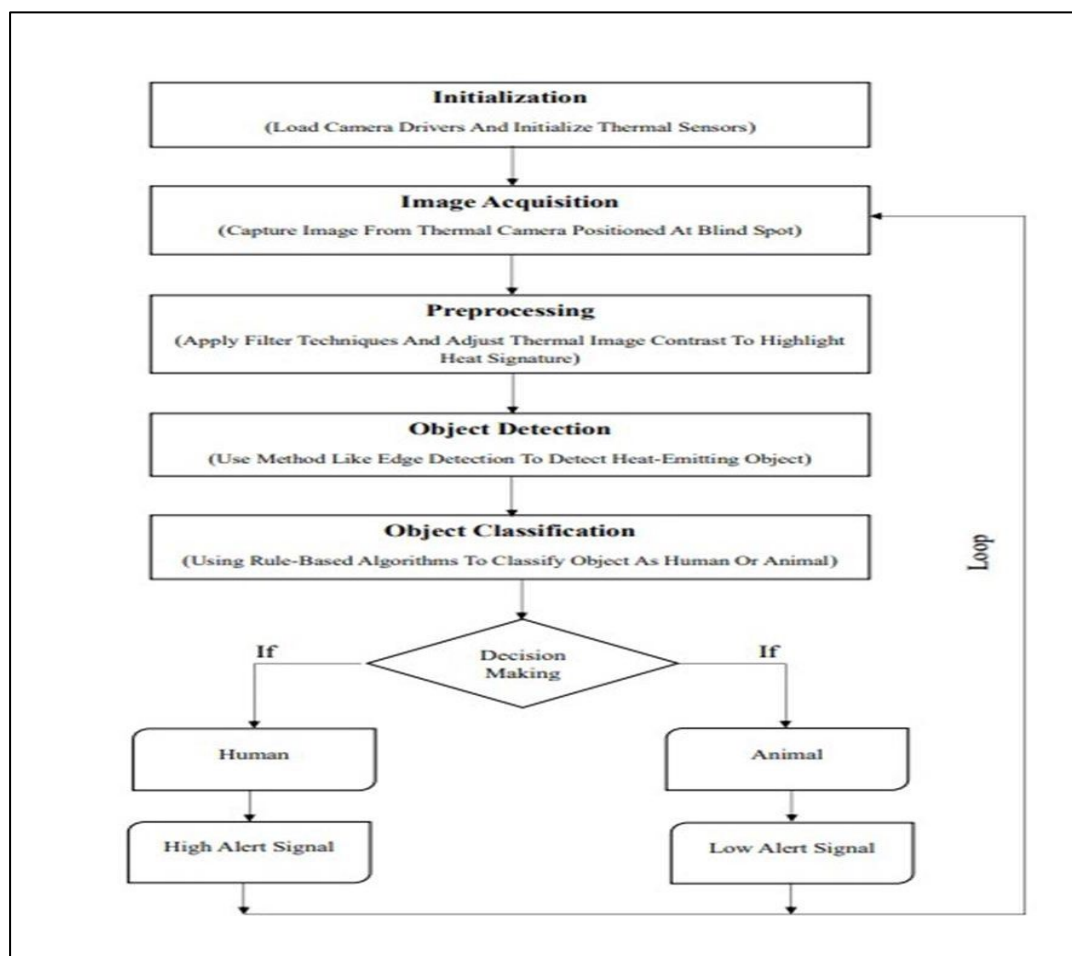


Fig 1 Flow Chart of Blind Spot Safety Using Thermal Image Processing For Heavy Vehicles

III. CONCLUSION

The integration of thermal imaging with advanced processing techniques demonstrates significant improvements in blind spot safety for heavy vehicles. This system addresses key limitations of traditional methods, providing robust performance in low-visibility conditions. Future work includes integrating this technology with LiDAR and GPS for enhanced situational awareness and automating fleet safety monitoring systems.

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